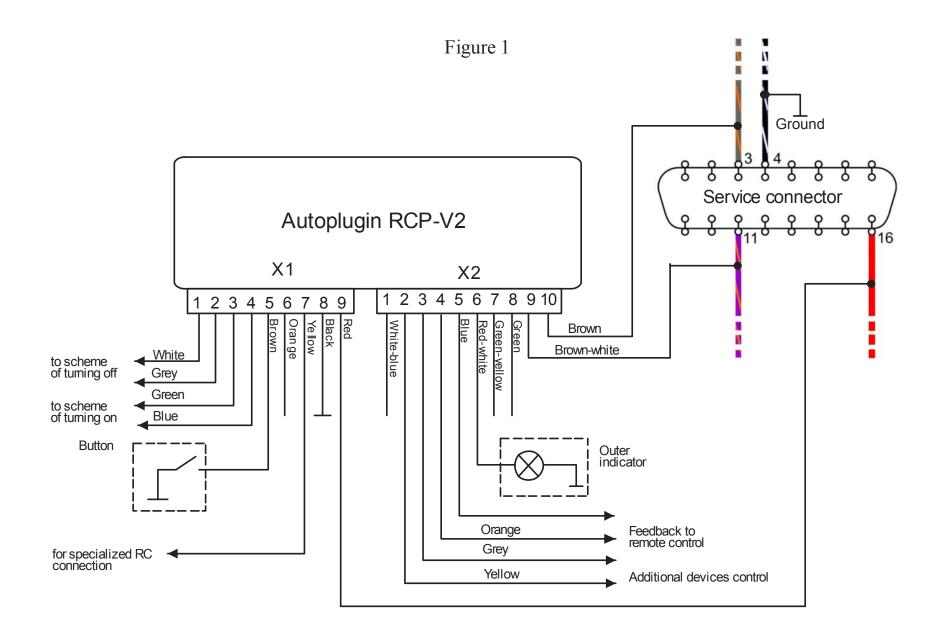
# **Autoplugin RCP-V2**

**Installation Manual** 



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## 1) Installation procedure for plug-n-play connection

- Find the service connector at the left side of the dashboard, below the lighting control switch.
- Open the case of the service connector (if applicable).
- Pass PnP-cable wires with white connectors on the end inside the dashboard, beside of the service connector. Pull the wires inside the dashboard.
- Connect white connectors of PnP-cable to RCP
- Connect black connector of PnP-cable to the car's OBD-connector.
- Turn ignition on to let the module get information from CAN-bus and wait until LED goes off. Turn ignition off.
- Check for the heater remote start by using Volvo key: turn on perimeter lighting, then press Lock button twice.
- Find place under the dashboard for the module and fix it with adhesive tape.
- Shorten length of the cable by the strap
- Close the case of the service connector (if applicable)

**Note**: if you need to unplug PnP-cable from OBD-connector (ex. to connect diagnostic equipment to the car's electronic system), don't pull for the wires of the cable! Pull for the housing of connector or for the special strap (if applicable).

## 2) Connection schemes for permanent connection

• General connection scheme (fig.1, page 2)

Explanations to the scheme:

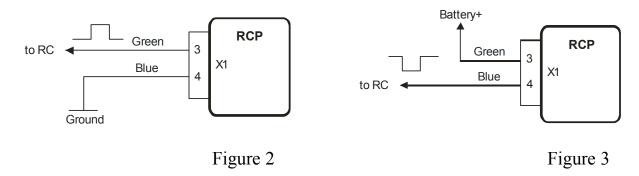
- o It is enough to connect power wires (X1.8, X1.9) and CAN-bus wires (X2.9, X2.10) to the module to obtain a possibility to start the heater using Volvo remote key. You can use supplied PnP-cable for such a connection.
- o The car's wiring marked in colour.
- o Optional elements are outlined by dashes

## Connection of the inputs Heater\_on± and Heater\_off±

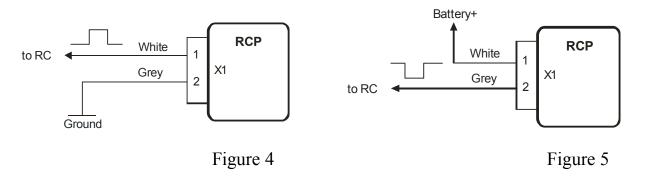
You can connect and use set of devices as a remote control of the fuel-fired heater: specialized heater remotes (such as Telestart, EasyStart, Smart Start), additional alarm systems remote controls, GSM mobile phones in conjunction with automotive GSM-modules, etc.

If the remote control has output channels that give short impulses in active state, it is possible to apply the schemes given at fig. 2-6. The remote control with two independent channels can separately turn the heater on and off.

o The fig.3 presents the scheme to turn the heater on by the impulse of positive polarity. The fig.4 presents the scheme to turn the heater on by the impulse of negative polarity.



o The fig.4 presents the scheme to turn the heater off by the impulse of positive polarity. The fig.5 presents the scheme to turn the heater on by the impulse of negative polarity.



o The remote control with the only one output line may be connected by the scheme at fig. 6 to add a possibility not only to turn the heater on, but also turn the heater off too. Every one impulse on the output line of the remote control receiver unit will move the heater to the opposite state: switch on idle heater, switch off operated heater. To realize this mode it is necessary to connect in pairs the inputs Heater\_on+ with Heater\_off+, and also the inputs Heater\_on- with Heater\_off-.

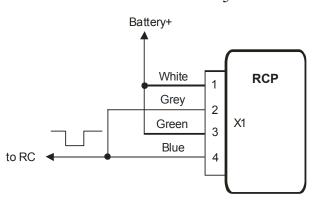


Figure 6

## • Connection of the input RC\_in

o The input RC\_in is intended for connection of specialized remote controls such as DEFA Smart Start, Hydronic Easy Start, Webasto Telestart. If direct connection of remote control's output line to the input RC\_in is not functional, the scheme at the fig.7 can be applied.

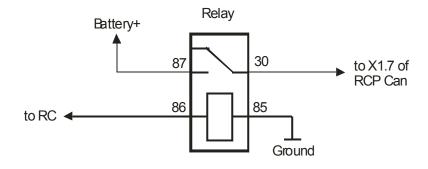


Figure 7

Some GSM modules control external device by the means of inner relay.
These may be connected to RCP by the scheme at the fig.8

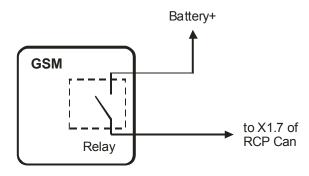


Figure 8

### Alerts receiving

If the remote control unit has got inputs to obtain information about the heater operation, they can be connected to the RCP's outputs Alert\_1 and Alert\_2. The outputs have negative polarity. Therefore if remote control unit not fit it, it needs to apply a matching circuit (with relay ex.).

Events given on the outputs Alert\_1 and Alert\_2 are adjusted by the settings 7.3 and 7.4 accordingly. Also the output line Timer\_out can be used to send notification how much time the heater operates.

### Status output line application

1. Indication of the heater operation by the hazard warning flashers (in addition to the direction indicators in rear-view mirrors).

The module can indicate of the heater operation by hazard flashers. Connect the module's output X2.2 to the grey-red wire (pin 3 of the connector) of the hazard warning switch, and choose the settings 7.5.3 (the settings 6.2-6.7 also need to be adjusted) for this purpose.

## 3) Installation procedure for permanent connection

#### General recommendations

The required tools: Torx screwdriver, wire cutter, wire stripper.

- Remove the panel around the service connector on the left side of the dashboard
- Find place inside the dashboard to install the module (mounted on double-sided tape)
- Connect the module to car's wiring according to the scheme at the fig.1. Connect the module to the receiver unit of remote control, according to the schemes at the figures 3-9. Make task specific connections, if necessary. The module is powered and connected to the CAN-bus wires near the service connector using quick splice connectors (supplied).

The module's power (pin X1.9) connects to the orange wire of service connector (pin 16), the module's signal ground (pin X1.8) – to the black-white wire of service connector (pin 4).

The signal «CAN-L» (pin X2.9) connects to the violet-orange wire (pin 11), the signal «CAN-H» (pin X2.10) – to the grey-orange wire (pin 3). Twist brown and brown-white wires of the connector X2 to the pair before connections. It is not recommended to lengthen these wires.

- Connect both connectors to the module (X2 should be connected first)
- Test the heater start from the module
- Fix the module using double-sided adhesive tape
- Install interior elements in the reverse order of removal
- Adjust the module in the programming mode if it necessary. Make notes in the programming table of the user manual about the adjustments

## 4) Troubleshooting

If you have problems with module operation, first of all check indication of the built-in LED. LED blinks on for a 10 second after powering and then has to turn off (CAN-bus have to be awoken). If a run-time error appears at heater startup, LED indicates an error by flashings. The number of flashes corresponds to the error code. See table 1 for the codes description and possible solutions.

Table 1

Error	Error	Possible Reasons of	Solutions
Code	Description	Error Appearance	
2	No answer from the heater	The heater is not activated in the CIP	Configure the heater by Volvo car dealer's equipment
	followed the start command	Outer temperature is upper than +15 Celsius degrees	The heater works only at environmental temperatures below +15°C. It is heater manufacturer's restriction
		Fuel level in the tank is close to empty ("Fuel Low" warning indicator is lighting in the CIP)	Refuel the car
		The heater is blocked after 3 unsuccessful starts	Try to start the heater from the CIP's menu. If it not started to burn, make diagnostics of the heater.
3	Battery level is low	The module has determined that the battery voltage at the heater startup or during the heater operation is below the specified settings 3.1 и 3.2	Charge car's battery with special charger (or start engine to charge) or cancel 3.1/3.2 module's settings

4	Time limits exceeded	Time limit for autonomous operation of the heater is achieved (with applied setting 1.1)	Run the engine or cancel 1.1 setting
5	Unsuccessful start	The heater was switched off spontaneously at startup	Make diagnostics of the heater if the error appears again
6	Operation cycle too short	The heater was switched off spontaneously with operating time of less than 20 minutes	Make diagnostics of the heater if the error appears again
8	CAN-bus error	The lines X2.9 и X2.10 connected incorrectly	Check the lines connection
9	Settings error	Settings have been incorrectly stored in RCP's memory	Reset the settings (8.1.1), readjust RCP
11	Heater no connection	The heater is unplugged from CANbus or is out of order	Make diagnostics of the heater
12	Unknown CAN-bus	CAN-bus type has not been determined	Check for compatibility of RCP module with the car. Try to set the CAN-bus code manually*

<sup>\*</sup> Information available on request